

P3800 Computational Physics

Nearly all problems in science today require

- approximations
- computers, often big ones, for
 - 1 - Calculus: integration, differentiation, solving ODE's and PDE's
 - 2 - Matrices (Linear algebra): solving systems of eqⁿ's, eigenvalues
 - 3 - Simulations: many degrees of freedom yield emergent behaviour, e.g. particles crystallization

Three main tools to investigate physical phenomena

- 1 - Experiment
- 2 - Mathematical Physics - paper and pencil theory
- 3 - Computation

All "easy" problems were solved long ago (by defⁿ?) and involved simplifying assumptions

- e.g.
- projectile motion \rightarrow neglect air resistance
 - spring force $F = -kx$ valid for small oscillations

- (QM) H-atom can be solved exactly, but He and H^- require heavy computations

For system with many particles / degrees of freedom

- e.g. - molecules in a liquid
- star in a galaxy
- electrons in a metal
- climate model

computational methods are often the only way to get useful results.

When number of particles is too large to handle directly, their effects are modelled in a statistical way, e.g. Brownian motion

Computational Physics - two main branches
(although separation is not always clear)

- solving equations e.g. $F = ma$

Theory yields an eqⁿ that describes the system (e.g. projectile). Solving that eqⁿ yields a theoretical realization of the system (projectile's trajectory).

- simulations : No analytic theory for describing the phenomenon of interest. Instead, use theory of underlying components of a system and see how phenomenon arises.

e.g. Pressure in a container full of a non-ideal gas.

In all cases computations involve discrete manipulation of stored information

calculus \rightarrow discretized representation of continuous variables

" x " \rightarrow $x_1, x_2, x_3 \dots$

and equations (ODE's, PDE's)

Infinitesimal differences not possible $\frac{dy}{dx} \rightarrow \frac{y_{i+1} - y_i}{x_{i+1} - x_i}$
 \rightarrow Taylor series / expansion is a big tool.

simulations \rightarrow e.g. particles, discrete by nature.

This course is a first step towards high performance computing (HPC) to solve physical problems

Main languages of HPC today are C, C++, Fortran
(see Computer Basics slides)

16-bit floating point example

$\begin{cases} 1 \text{ sign bit} \\ 5 \text{ bits for exponent} \\ 10 \text{ bits for mantissa} \end{cases}$

$$11/2 = 5.5$$

$$(5)_{10} = (101)_2 \quad (1 \times 2^2 + 0 \times 2^1 + 1 \times 2^0)$$

$$(0.5)_{10} = (0.1)_2 \quad (1 \times 2^{-1} = 0.5)$$

$$\begin{aligned} \therefore (5.5)_{10} &= (101.1)_2 \quad \text{exponent} \\ &= (1.011)_2 \times (2)_{10} \end{aligned}$$

leading 1 is the hidden bit
10-bit mantissa m
0110000000

$$\text{exponent} = a - \text{bias}$$

$$2 = a - 15$$

$$a = (17)_{10} = (10001)_2$$

16-bit bitstring for $(5.5)_{10}$

sign bit \rightarrow (+ve is 0)
0 10001 011000000000
a m

Convert 19.13 to binary

$$\begin{array}{rcll} 19 \div 2 = 9 & \text{remainder} & 1 & \leftarrow \text{this is the least significant bit} \\ \downarrow & & & \\ 9 \div 2 = 4 & \text{r} & 1 & \\ \downarrow & & & \\ 4 \div 2 = 2 & \text{r} & 0 & \\ \downarrow & & & \\ 2 \div 2 = 1 & \text{r} & 0 & \\ \downarrow & & & \\ 1 \div 2 = 0 & \text{r} & 1 & \leftarrow \text{most sig. bit} \end{array}$$

$$(19)_{10} = 10011$$

$$\begin{array}{rcll} 0.13 \times 2 = 0.26 & \text{carry} & 0 & \leftarrow \text{most sig. bit} \\ 0.26 \times 2 = 0.52 & \text{carry} & 0 & \\ 0.52 \times 2 = 1.04 & \text{carry} & 1 & \\ \downarrow & & & \\ 0.04 \times 2 = 0.08 & \text{carry} & 0 & \\ 0.08 \times 2 = 0.16 & \text{carry} & 0 & \\ 0.16 \times 2 = 0.32 & \text{c} & 0 & \\ 0.32 \times 2 = 0.64 & \text{c} & 0 & \\ 0.64 \times 2 = 1.28 & \text{c} & 1 & \\ 0.28 \times 2 = 0.56 & \text{c} & 0 & \dots \end{array}$$

$$(19.13)_2 = 10011.001000010\dots$$