

Rewrite Taylor series

$$(1) f(x-h) = f(x) - hf'(x) + \frac{h^2}{2} f''(x) - \frac{h^3}{3!} f'''(x) + \dots$$

$$(2) f(x+h) = f(x) + hf'(x) + \frac{h^2}{2} f''(x) + \frac{h^3}{3!} f'''(x) + \dots$$

subtract: (2) - (1)

$$\star f(x+h) - f(x-h) = 2hf'(x) + 2\frac{h^3}{3!} f'''(x) + O(h^5)$$

$$f'(x) = \frac{f(x+h) - f(x-h)}{2h} + O(h^2)$$

$$f'_i = \frac{f_{i+1} - f_{i-1}}{2h} + O(h^2) \quad \text{Centred difference or 3-point formula}$$

add: (1) + (2)

$$f_{i+1} + f_{i-1} = 2f_i + h^2 f''_i + O(h^4)$$

$$f''_i = \frac{f_{i+1} - 2f_i + f_{i-1}}{h^2} + O(h^2)$$

Can generate higher order differences

$$\text{E.g. } f(x+2h) - f(x-2h) = 4hf'(x) + 2\frac{(2h)^3}{3!} f'''(x) + O(h^5)$$

$$\frac{8h^3}{3} f'''(x) = f(x+2h) - 4hf'(x) - f(x-2h) + O(h^5)$$

↳ plug into \star to get

$$f'(x) = \frac{1}{12h} [f(x-2h) - 8f(x-h) + 8f(x+h) - f(x+2h)] + O(h^4)$$

5-point formula

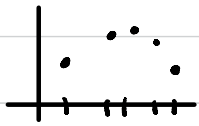
$$f'_i = \frac{1}{12h} (f_{i-2} - 8f_{i-1} + 8f_{i+1} - f_{i+2}) + O(h^4)$$

described as $\left\{ \begin{array}{l} \text{accurate to order } h^4 \\ 4^{\text{th}}\text{-order accurate} \\ \text{truncation error is } O(h^4) \end{array} \right.$

As we have seen, subtraction reduces precision, so it is advantageous to reduce the number of subtractions

$$f'_i = \frac{1}{12h} \left[(f_{i-2} + 8f_{i+1}) - (f_{i+2} + 8f_{i-1}) \right]$$

Non-uniformly spaced data



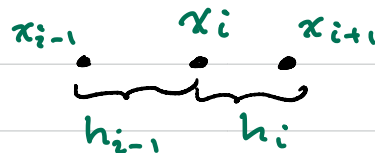
$$\Delta x_i = x_{i+1} - x_i \neq \text{constant}$$

one option: fit data to analytic function and then take derivative

- useful if there is theoretical motivation for the fit

- can introduce artefacts: extra peaks, rounded kinks

define $h_i = x_{i+1} - x_i$
 $h_{i-1} = x_i - x_{i-1}$



$$x_{i+1} = x_i + h_i$$

$$x_{i-1} = x_i - h_{i-1}$$

Write Taylor series

$$f(x_{i+1}) = f(x_i) + (x_{i+1} - x_i) f'(x_i) + \frac{1}{2} (x_{i+1} - x_i)^2 f''(x_i) + \dots$$

or $f_{i+1} = f_i + h_i f_i' + \frac{1}{2} h_i^2 f_i'' + \mathcal{O}(h^3)$

$$f_{i-1} = f_i - h_{i-1} f_i' + \frac{1}{2} h_{i-1}^2 f_i'' + \mathcal{O}(h^3)$$

algebra \downarrow (eliminate f_i'')

$$f'(x_i) = f_i' = \frac{h_{i-1}^2 f_{i+1} + (h_i^2 - h_{i-1}^2) f_i - h_i^2 f_{i-1}}{h_i h_{i-1} (h_i + h_{i-1})} + \mathcal{O}(h^2)$$

3-point formula for non-uniform data

Richardson Extrapolation

Can construct algorithms to get derivatives to arbitrary order (but using higher order methods means assuming f'' is smooth)

For $f'(x)$: Let $\Delta_1(h) = \frac{f(x+h) - f(x-h)}{2h}$

$$\Delta_1(h) = f'(x) + \mathcal{O}(h^2)$$

can show that (5-pt formula)

$$\Delta_1(h) - 4\Delta_1\left(\frac{h}{2}\right) = -3f'(x) + \mathcal{O}(h^4)$$

and $\Delta_1(h) - 20\Delta_1\left(\frac{h}{2}\right) + 64\Delta_1\left(\frac{h}{4}\right) = 45f'(x) + \mathcal{O}(h^6)$

etc

Can determine the coefficients for higher orders systematically

write $\Delta_1(h) = \frac{f(x+h) - f(x-h)}{2h} = f'(x) + \sum_{k=1}^{\infty} C_{2k} h^{2k}$

call $\Gamma_{k0} = \Delta_1\left(\frac{h}{2^k}\right)$

can show

$$\Gamma_{kl} = \frac{4^l}{4^l - 1} \Gamma_{k, l-1} - \frac{1}{4^l - 1} \Gamma_{k-1, l-1}$$

for $0 \leq l \leq k$ leads to

$$f'(x) = \Gamma_{kl} - \sum_{m=l+1}^{\infty} B_{m,l} \left(\frac{h}{2^k}\right)^{2m}$$

where $B_{kl} = \frac{4^l + 4^k}{4^l - 1} B_{k, l-1}$

and

$$B_{kk} = 0$$

Example: $k=1, l=1$

$$f'(x) = \Gamma_{11} - \sum_{m=2}^{\infty} B_{m1} \left(\frac{h}{2}\right)^{2m}$$

$$f'(x) = \frac{4^1}{4^1-1} \Gamma_{10} - \frac{1}{4^1-1} \Gamma_{00} + \mathcal{O}(h^4)$$

$$\Gamma_{00} = \Delta_1(h)$$

$$\Gamma_{10} = \Delta_1(h/2)$$

$$f'(x) = \frac{4}{3} \Delta_1(h/2) - \frac{1}{3} \Delta_1(h) + \mathcal{O}(h^4)$$

or $\Delta_1(h) - 4\Delta_1(h/2) = -3f'(x) + \mathcal{O}(h^4)$ as before

Can apply similar method for higher order derivatives

$$\begin{aligned} \text{Let } \Delta_2(h) &= \frac{f(x+h) - 2f(x) + f(x-h))}{h^2} \\ &= f''(x) + \mathcal{O}(h^2) \end{aligned}$$

Can show

$$\Delta_2(h) - 4\Delta_2(h/2) = -3f''(x) + \mathcal{O}(h^4)$$

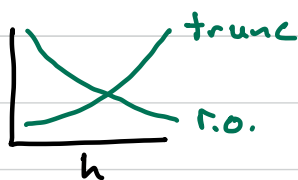
same form as with $f'(x)$ but with

Δ_1 replaced with Δ_2

Error analysis

as h decreases

truncation errors decrease but
roundoff error from subtraction
increases



$$\text{error } \epsilon = \epsilon_{\text{trunc}} + \epsilon_{\text{roundoff}}$$

ϵ is minimized when $\epsilon_{\text{trunc}} \approx \epsilon_{\text{r.o.}}$

$\epsilon_{\text{r.o.}}$ from subtraction $\frac{f(x+h) - f(x)}{h}$ is $\epsilon_{\text{r.o.}} \approx \frac{\epsilon_M f(x)}{h}$

ϵ_{trunc} : forward difference
 $\mathcal{O}(h), \approx \frac{h}{2} f''(x)$

centred diff
 $\mathcal{O}(h^2), \approx \frac{h^2}{3} f'''(x)$

minimum error (best you can get) when $\epsilon_{\text{r.o.}} \approx \epsilon_{\text{tr}}$

$$\frac{f \epsilon_M}{h_{\text{FD}}} \approx \frac{h_{\text{FD}}}{2} f''$$

$$\frac{f \epsilon_M}{h_{\text{CD}}} \approx \frac{h_{\text{CD}}^2}{3} f'''$$

Assume for simplicity $f \approx f' \approx f'' \approx f''' \approx 1$, $\epsilon_M \approx 10^{-15}$ double prec.

$$h_{\text{FD}} \approx (2 \epsilon_M)^{1/2} \approx 4 \times 10^{-8} \quad h_{\text{CD}} \approx (3 \epsilon_M)^{1/3} \approx 2 \times 10^{-5}$$

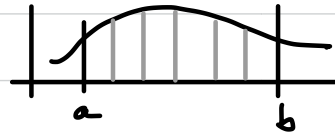
$$\epsilon_{\text{FD}} \approx \frac{\epsilon_M}{h_{\text{FD}}} \approx 3 \times 10^{-8} \quad \epsilon_{\text{CD}} \approx \frac{\epsilon_M}{h_{\text{CD}}} \approx 5 \times 10^{-11}$$

Centred d.f.f. gives smaller optimal error with a larger step size.

Integration

$$I = \int_a^b f(x) dx$$

area
→
under
curve



Before computers, approximated areas with quadrilaterals
- approach called numerical quadrature

Recall Riemann definition / rectangle rule

sum over rectangular areas, take limit as

width $h = x_{i+1} - x_i \rightarrow 0$

$$I = \lim_{h \rightarrow 0} \sum_{i=1}^{\frac{b-a}{h}} h f(x_i)$$

For finite h ($h \neq 0$), in general

$$\int_a^b f(x) dx = \sum_{i=1}^N f(x_i) \omega_i \quad \text{for } N \text{ points in } [a, b]$$

- different algorithms yield different "weights" ω_i
(for rectangles $\omega_i = h$)

Trapezoid rule

- use N points spaced evenly apart by h

$$x_i = a + (i-1)h, \quad i = 1, \dots, N$$

- there are $N-1$ intervals $h = \frac{b-a}{N-1}$

- over each interval, area is approximated by area of trapezoid



$$A_i = h \frac{1}{2} (f_i + f_{i+1}) = \frac{h}{2} f_i + \frac{h}{2} f_{i+1}$$