$$I = \int_{a}^{b} f(x) dx =$$
  
=
  
(each point, except first and last, is involved with two trapezoids)
  
 $I_{\tau} = \sum_{i=1}^{N} f(x_i) \omega_i$ ,  $\xi \omega_i \xi =$ 
  
What is the truncation error?
  
 $f(x) = e_i^{\alpha} f_{i+1}$  in Taylor series
  
 $f_{\epsilon} =$ 
  
=
  
 $\int_{a}^{x_{i+1}} f_{\epsilon} dx =$ 
  
 $x_i$ 

Compare with integral of f(x)  $\int f dx =$ h<sup>3</sup> term using fy differs from result based on Taylor series expansion of f ... Truncation error in one step Error over N steps is What about roundoff error ? At each step so if turns out For Em ~ 10<sup>-16</sup> and smallest error occurs when

Simpson's Rule  
Consider a portion of an  
integral from  
Approximate f(x) with a  

$$f_{(x)} =$$
  
 $I = \int_{x_{i,1}}^{x_{i,1}} [f_i +$   
 $= (x_{i,1} - x_{i,1})f_i +$   
 $= 2hf_i$   
 $= 2hf_i$ 

Note: This is equivalent to fitting a quadratic function through (xi-1,fi), (xi,fi) and (xi+1,fi+1) (cubic term contributes zero to the integral).

Break up entire integral into Break up entire integral into an N is N must ×5 x3 0 · x,  $\mathbb{I}_{s} = \underbrace{h}_{z} \left( f_{1} + 4f_{2} + f_{3} \right)$  $= \frac{h}{2} \int f_1 + 4f_2$ truncation error is so étrunc is とう In terms of general form for numerical integration Is=

Note: consider N=3

 $\{\omega_i\}=$  $\sum_{i=1}^{N} \omega_i =$ This is generally true for all integration algorithms N $\sum_{i=1}^{N} \omega_i =$ Best error, optimal h: as always Ero ≈ (again, for b-a ~ f ~ etc ~ 1) Em ~ Em ≃ hoptimal ~ Ebest ≈

Method of Undetermined Coefficients

Consider writing f(x) as  $f(x) \simeq$ on a small interval

General integration formula  $\int_{\alpha}^{\beta} f(x) dx =$ with i=1,2,

becomes  $\int_{0}^{\tilde{b}} \sum_{n=1}^{p} C_n x^n dx =$ 

 $\rightarrow \int_{x}^{b} dx x^{n} =$ for each n e o, ... p 3

$$n=0 \quad \tilde{b}-\tilde{a} =$$

$$n=1 \quad \frac{\tilde{b}^{2}-\tilde{a}^{2}}{2} =$$

$$n=2 \quad \frac{\tilde{b}^{3}-\tilde{a}^{3}}{3} =$$

$$r, \quad n=1 \quad r$$

$$r, \quad n \text{ matrix form}$$

$$\begin{pmatrix} 1 & 1 & \dots & 1 \\ X_{1} & & \\ & & \end{pmatrix} \begin{pmatrix} \omega_{1} & & & \\ & b-\tilde{a} & \\ & & & \\ & & & \end{pmatrix} \begin{pmatrix} \omega_{1} & & & \\ & b-\tilde{a} & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & &$$