

The midpoint method is an example of a

↳ use function calls to
→ need to find

To obtain R-K scheme for

write $y(t+h) =$

$$y'(t) = \frac{dy}{dt} =$$

$$\frac{d^2y}{dt^2} =$$

$$\frac{d^3y}{dt^3} =$$

$y(t+h) =$

Can also write

$$\star y(t+h) =$$

where $c_1 =$

$c_2 =$

$c_3 =$

$c_m =$

Example $m=2$ (2nd order RK)

- keep terms

$$y(t+h) =$$

(Taylor)

$$\star y(t+h) =$$

$$c_1 =$$

$$c_2 =$$

$$\text{so } y(t+h) =$$

=

compare with Taylor series

- freedom to choose some parameters

Let's choose $\alpha_1 = 0 \rightarrow$

then $y_{i+1} =$

$$c_1 =$$

$$c_2 =$$

This is the
Midpoint method

or, e.g. choose $\alpha_1 = \frac{1}{2} \rightarrow$

$$y_{i+1} =$$

$$c_1 =$$

$$c_2 =$$

rewrite as

"Predictor
Corrector
Method"
 $\tilde{y}_{i+1} =$
 $y_{i+1} =$

Common algorithm based on

"the" RK method, "Classical RK"

$$y(t+h) =$$

$$c_1 =$$

$$c_2 =$$

$$c_3 =$$

$$c_4 =$$

As with RK2,

Adaptive Time Step

- Algorithm chooses time step to give
- can significantly

→ at each step, make sure

→ h needs to be

Simplest case:

- want to step from t to $t+h$ in one jump:

and

two jumps:

Error in y_{n+1}^* is \approx

Error in y_{n+1} is \approx

so $\Delta \equiv$

is a good estimate of the error.

Now stipulate that we want the
to be smaller than a

If ϵ , accept
 $\rightarrow y(t+h) =$

or, we might get a slightly better estimate by
setting Δ since Δ is an
estimate of

(This will reduce the truncation error per step to $\mathcal{O}(h^3)$.)

Should also consider ϵ , either
by Δ or by increasing by a
factor involving

If ϵ , we need to Δ and try again.

option ①

option ②

Simple example

$$\frac{dy}{dx} = \cos(x)$$

Note: RHS does not depend on y .

$$y(0) \quad \text{on} \quad x \in [0, 2\pi]$$

The same approach can be applied to

$$y(x+2h) =$$
$$y(x+2h) =$$

full step of
two steps each of

$$(C \sim) \quad \Delta \equiv$$
$$=$$
$$\Delta \propto$$

If $\Delta < \epsilon$, set
or
set

for a possible improvement (assuming)
and make

If $\Delta > \epsilon$,

==

If the current step size
want to produce an error of

expect $h_{\text{new}} =$, so set
where is a "safety factor."

How "expensive" is this variable step size approach?

Number of function evaluations is

→ actually only

"cost" of this variable step size approach is

since we could get the better accuracy of

, which takes