

## von Neumann Stability Analysis

Recall solution to the wave eq<sup>n</sup>  $\frac{\partial^2 u}{\partial t^2} = c^2 \frac{\partial^2 u}{\partial x^2}$  by Sep. of variables

$$u(x,t) =$$

We've seen that  $\frac{\partial^2 y}{\partial x^2} \rightarrow$  with A

So the separated eq<sup>n</sup>s are  
and the

The sol<sup>n</sup> is of the form  $\sum_m (a_m \sin \omega_m t + b_m \cos \omega_m t) \sin k_m x$

so consider a contribution to the discretized solution

$$u_j^n \approx$$

or generally  $u_j^n =$

eigenmode contribution to sol<sup>n</sup> with  $k = \frac{2\pi}{\lambda}$   
How does it grow in time?

Increasing time means

Solution is unstable if

Recall "simple" algorithm for advection eq<sup>n</sup>

$$u_j^{n+1} =$$

sub in  $u_j^{\hat{}}$  =

$$\sum e =$$

$$\sum =$$

$$\Rightarrow |\xi|$$

For Lax Method

$$u_j^{n+1} =$$

## Elliptic Equations - PDEs in matrix form

We've already seen 1-D Poisson eq<sup>n</sup>. Now 2-D

$$\text{discretize: } x_j = \\ y_l =$$

$$\text{using } \frac{\partial^2}{\partial x^2} \rightarrow$$

gives

ASIDE: Can rearrange eq<sup>n</sup>

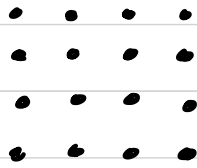
$$u_{j,l} =$$

i.e.  $u_{j,l}$  is the average value of its neighbours plus a direct contribution from  $p$ . This forms the basis for relaxation methods, the simplest of which plugs in old values of  $u_{j,l}$  in the RHS to generate new values - iterating until results converge (Jacobi method).

Want to make a single (not 2-D matrix).

$$\text{call } z = \quad \text{for } j = 0, 1, \dots, J \text{ and} \\ l = 0, 1, \dots, L$$

e.g.  $J = L = 3$  ( $4 \times 4$ )



$j=0 \rightarrow i=$  (column 1)  
 $j= \rightarrow i=$   
 $j= \rightarrow i=$   
 $j= \rightarrow i=$

$(j, l) = (0, 0)$   
 $i =$

for  $j \rightarrow j+1, i \rightarrow$   
 $j \rightarrow$   
 $l \rightarrow$   
 $l \rightarrow$

Difference eq<sup>n</sup>  $u_{j+1, l} + u_{j-1, l} + u_{j, l+1} + u_{j, l-1} - 4u_{j, l} = h^2 \rho_{j, l}$   
becomes

$\nearrow$   
4 neighbours of

holds only at  
 $j=$

$l=$

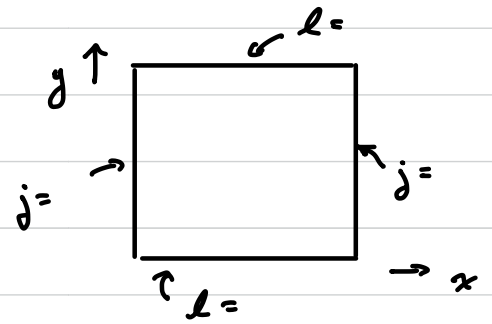
At boundary points:

$$j = \rightarrow i =$$

$$j = \rightarrow i =$$

$$l = \rightarrow i =$$

$$l =$$



must specify either  $u$  or its derivative

E.g. If, say,  $\frac{\partial u}{\partial x} \Big|_{x_J, y} = 0$

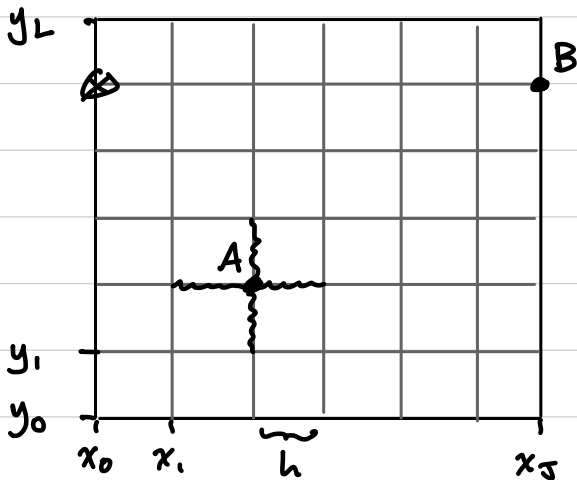
$\rightarrow$

$$= 0 \rightarrow$$

or  $u_{\text{rightboundary}} = u_{\text{rightboundary} - ( \quad )}$

with  $i_{\text{rightboundary}}$  given above for  $j = J$  case

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2<sup>nd</sup> derivative at an interior point A is evaluated using 4 nearest neighbours ( $j \pm 1, l \pm 1$ ) and itself ( $j, l$ )

- Boundary points B must be specified

or

- With periodic boundary conditions

2<sup>nd</sup> derivative at B involves point  $\otimes$

Solving the PDE reduces to solving  
where  $A$  is  
a.k.a.


Each sub-block is

There are                      sub-blocks  $\rightarrow A$  is

Use linear algebra routines for band matrices

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Names of relaxation methods include

- Gauss-Seidel
- Successive Over-Relaxation