Anomalous dynamics in tracer-particle motions in an electrohydrodynamically driven oil-in-oil system

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We characterize the superdiffusive dynamics of tracer particles in an electrohydrodynamically driven emulsion of oil droplets in an immiscible oil medium, where the amplitude and frequency of an external electric field are the control parameters. In the weakly driven electrohydrodynamic regime, the droplets are trapped dielectrophoretically on a patterned electrode, and the driving is therefore spatially varying. We find excellent agreement with a $\langle x^2 \rangle \sim t^{1.5}$ power law and find that this superdiffusive dynamics arises from an underlying displacement distribution that is distinctly non-Gaussian and exponential for small displacements and short times. While these results are comparable with a random-velocity field model, the tracer particle speeds are in fact spatially varying in two dimensions, arising from a spatially varying electrohydrodynamic driving force. This suggests that the important ingredient for the superdiffusive $t^{1.5}$ behavior observed is a velocity field that is isotropic in the plane and spatially correlated. Finally, we can extract, from the superdiffusive dynamics, a experimental length scale that corresponds to the lateral range of the hydrodynamic flows. This experimental length scale is non zero only above a threshold ion mobility length.

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I. INTRODUCTION

Diffusion is characterized by a mean-squared displacement that increases linearly with time: in one dimension, $\langle x^2 \rangle = 2Dt$, and the underlying distribution of displacements is Gaussian. However, in many systems in colloid science and biology, it has been recognized that a relation of the form $\langle x^2 \rangle \sim t^{\gamma}$ holds, with $\gamma \neq 1$. This is often termed anomalous transport. Apart from simple ballistic motion (corresponding to $\gamma = 2$), there are two categories of observed anomalous motion: subdiffusive ($0 < \gamma < 1$) and superdiffusive ($\gamma > 1$).

Anomalous transport that is subdiffusive or superdiffusive can be observed in biological cells [1-4]. The essential ingredients that generate anomalous motions are macromolecular crowding (which can restrict motions) and active driving (which can enhance motions). Subdiffusive motions have been extensively studied in the context of macromolecular crowding [3,5,6].

Enhanced, superdiffusive dynamics, while less common, is particularly relevant to (active or driven) systems out of equilibrium. A number of theoretical studies have found reasons for superdiffusive behavior. Ajdari [7] considered a model where particles diffuse until they are reversibly adsorbed onto active filaments which propel them. Bouchaud *et al.* [8], Zumofen et al. [9], and Redner [10] found superdiffusive motions arises when there are random, but spatially correlated velocity fields. These motions, in the context of the random velocity model, arise from a probability distribution of the form $P(x, t) \sim t^{-3/4} e^{-(x/t^{3/4})^{\delta}}$, where $\gamma = 1.5$, but δ is not known. In a numerical study of Lévy random walks [11], which describe nondiffusive transport that is characterized by a coupling between free-path length and free-path duration, Trotta et al. found superdiffusive transport with $\gamma \simeq 1.47$; the probability distribution function is a modified

Gaussian for short displacements but a power law for large displacements.

Following tracer-particle motions inside an eukaryotic cell, Caspi and coworkers [12,13] found enhanced diffusion, likely arising from microtubule-associated motor-driven motions rather than thermal motions, with an exponent $\gamma \sim 1.5$. Ott *et al.* [14] also found enhanced diffusion in a system of polymerlike micelles, where the enhancement could be killed by decreasing the breaking time of the micelle by increasing temperature. Gal *et al.* observe enhanced motions in polymer particles that are imbibed into living cancer cells [15], while Reverey *et al.* [16] see superdiffusion in intracellular motion in highly crowded cytoplasm.

Transitions from sub- to superdiffusive are seen in systems where the forcing exceeds a threshold that overcomes pinning on a surface [17]. Various groups have also reported on Brownian diffusion that can coexist with a non-Gaussian probability distribution of displacements [18–23], which possibly arise from competing effects at short and long times. Quite generally, this area of research is very active, and there is a call [1] for well-defined model systems that exhibit anomalous motions and, *at the same time*, allow single-particle tracking of tracerparticle dynamics.

The focus of this study is tracer-particle motions in an oilin-oil system driven by electrohydrodynamic driving forces. It has been shown previously [24,25] that one sees both steady circulations as well as unsteady motions as a function of the driving electric field, with the unsteady motions dominating at high amplitudes leading to chaotic motions and multiscale (seemingly turbulent) flows. In this work, we trap the oil droplets on a dielectrophoretic lattice, generating a spatially varying but periodic driving force. Given the high degree of control, the length scales on the tens of micrometers, and the presence of soft liquid-liquid interfaces, this system might be





FIG. 1. (a) A Side view of the cell geometry. Three dashed lines indicate three planes at which the experiment is conducted. The top plate is an unpatterned ITO electrode. The bottom electrode is patterned with circular ITO-free regions. Silicone oil is dielectrophoretically trapped in the ITO-free regions and assumes the form of near-hemispherical drops (shown in yellow). The continuous phase is castor oil, seeded with fluorescent PMMA particles (represented by white dots). (b) Snapshots of three planes of interest at (i) $h_p = 70$, (ii) 30, and (iii) 10 μ m above the patterned (bottom) electrode at $E = 4.6 \text{ V}/\mu\text{m}$, perpendicular to the page, and f = 1 Hz. The PMMA particles are the bright spots in each frame. Accumulation of PMMA particles at the interface of silicone oil drop and castor oil leads to a bright edge.

a clean and well-characterizable analog for out-of-equilibrium biological systems.

II. METHODS AND TECHNIQUES

A. Sample preparation and hardware

Figure 1(a) shows the side view of a sample cell with the electric field parallel to the page and to gravity. Two cover glass slides coated with indium tin oxide (ITO) are separated by glass spacers. The distance between the ITO slides is $h = 140 \ \mu m$. The bottom electrode is selectively etched out, using maskless patterning and photolithography, in the form of a hexagonal array of circular ITO-free regions, such that the diameter of each circle is approximately 50 μm and the nearest-neighbor center-to-center spacing, d_{nn} , is approximately 100 μm [25]. Ultraviolet-curable epoxies (Norland Optical Adhesive 61 and 68) are used to hold all parts together.

The cell is filled by pipetting an emulsion of silicone oil, dielectric constant $\varepsilon_{in}/\varepsilon_0 = 2.4$, conductivity $\sigma_{in} = 3.95 \times 10^{-11}$ S/m, and viscosity $\mu_{in} = 0.137$ Pas, and castor oil, dielectric constant $\varepsilon_{ex}/\varepsilon_0 = 3.6$, conductivity $\sigma_{ex} = 4.0 \times 10^{-10}$ S/m, and viscosity $\mu_{ex} = 0.819$ Pas, in a volume ratio of 1:16. The subscripts *in* and *ex* are used to represent the (silicone oil) droplet and the (castor oil) suspending carrier fluid, respectively. Fluorescent PMMA particles with diameter of 1 μ m are added to the carrier fluid, castor oil, in order to track the fluid flow.

The silicone oil drops are prepared, prior to recording the experiment, so that they are trapped at the ITO-free regions due to the negative dielectrophoretic force [25]. The

experiment is carried out at four field amplitudes, 3.5, 4.6, 5.8, and 7.0 V/ μ m, and for different sets of frequencies. These fields and frequencies are chosen with reference to the fieldfrequency phase diagram discovered in previous work [25], and all correspond to a region of parameter space that was identified as the "ordered regime" where the electrohydrodynamic flows are not strong enough to disrupt the hexagonal order of the trapped drops. Given that fluid flows in a leaky dielectric are governed by the boundary conditions at the interfaces, controlling the location of the interfaces enables us to follow tracer particle flows in the carrier fluid in a well-defined geometry. The experiment at each frequency and field amplitude is done at three different heights of sample cell, 10, 30, and 70 μ m above the patterned electrode, as shown by planes of interest in Fig. 1(a). Figure 1(b) shows a silicone oil drop surrounded by PMMA particles in castor oil and at three heights of interest.

A sinusoidal AC voltage, Tektronix model AFG3022 is amplified by a high-voltage amplifier, Trek model PZD2000A, whose output is applied the sample cell. Fluorescence microscopy is used to observe and record the image sequences.

B. Image processing

For each experiment, a stack of 400 images, each with an exposure time of 4 ms, was recorded with a water-cooled digital sCMOS camera (pco.edge 5.5) and an inverted microscope, Nikon Eclipse TE2000-U. The centroid, $\vec{r'} = (x', y')$, of each PMMA particle is first identified in each image.

The particle trajectory in time is then obtained by standard particle-tracking methods described by Crocker and Grier [26,27] using code programmed in IDL. Using the particle-tracking information one can obtain the mean-squared displacement in two dimensions, $MSD = \langle r^2(t) \rangle \equiv \langle [r'(t) - r'(t_0)]^2 \rangle$. $\vec{r}(t) = (x(t), y(t))$ [where $x(t) \equiv x'(t') - x'(t'_0)$ and $y(t) \equiv y'(t') - y'(t'_0)$, respectively] is the in-plane displacement of each particle as a function of time $t = t' - t'_0$, from a variable reference start time t'_0 . In the above, $\langle \cdot \rangle$ is an average over all the particles in the system and over the reference time. We are unable to access out-of-plane motions in real time, but we obtain the same 2D information at three depths in the sample.

The histogram of displacements, P(x, t) of all particles is calculated for a stack of 400 frames and for all field amplitudes, frequencies, and heights. The same was done for P(y, t).

C. Pattern formation and flow visualization

Prior to recording the experiments, the system (i.e., the droplet array) was prepared as follows. The electric field was set to $E = 7.0 \text{ V}/\mu\text{m}$ and f = 0.05 Hz. At very low frequency, in the regime of strong hydrodynamics where the hydrodynamic length, l_h , is on the order of hundreds of micrometers [25], large silicone oil drops are broken into many tiny droplets vigorously. The spontaneous breakup of droplets is a result of overcoming the viscous stresses by electric stresses at the interface of the droplets [24,28–30]. The strong inhomogeneous flows, with breakup accompanied by coalescence, can be achieved by either lowering the frequency or increasing the field amplitude. At a fixed field amplitude, the



FIG. 2. A time lapse series of 5 s for three heights of interest, from left to right $h_p = 70$, 30, and 10 μ m. Flows tracked by fluorescent PMMA particles are indicated by trails in direction of arrows from sources to sinks. For $h_p = 70 \ \mu$ m sources are at $d_{nn}/2 \simeq 50 \ \mu$ m, and sinks are at the center of the drops. For $h_p = 30$ and 10 μ m sources and sinks are located at edge of the drops and $d_{nn}/2 \simeq 50 \ \mu$ m, respectively, indicating an oblate drop deformation. Red circles show position of center of drops in the lower heights. $E = 5.8 \ V/\mu$ m, perpendicular to the page, $f = 3 \ Hz$, and scale bar is 50 μ m.

frequency is increased to f = 3 Hz. Increasing the frequency decreases the strength of the electrohydrodynamic flows but does not change significantly the dipolar contribution. The silicone oil drops coalesce and are attracted to the nearest ITO-free regions by negative dielectrophoresis, and an array of hexagonal silicone oil droplets, in castor oil, is created on the top of the patterned ITO slide [31].

All experiments are carried out at frequencies where the drops are always trapped on ITO-free regions. In steady state, toroidal flows known as Taylor vortices [32,33] are generated inside and outside of each droplet. In the context of the leaky dielectric model [32,33], these flows are generated by the tangential component of the electric stress at the interface of silicone oil drops and the surrounding castor oil medium; these are flows that arise from the accumulation of free charge carriers at these liquid-liquid interfaces. The PMMA fluorescent particles were used as tracer particles in order to visualize the outside flows: studying the nature of these flows is the main focus of this work.

Figure 2 shows a time lapse of 100 frames, equivalent to 5 s, of PMMA particles motion at three heights of interest. At 70 μ m above the patterned electrode (left panel), which is roughly 20 μ m above the top of the silicone oil drops, particle trajectories in the plane are less clear than for the lower heights, which are chosen to contain the silicone oil drops. Due to differences in the size of droplets, the flow pattern looks disordered and asymmetric. At lower distances from the patterned electrode, 30 and 10 μ m, middle and right panels, respectively, the flows are clearly initiated at the interface of silicone oil and castor oil. At steady state and for most of frequencies studied in this work, drops are oblate semi-ellipdoids with major axis perpendicular to the direction of the external electric field, and the circulation patterns are generated from equator to the poles [32,33], as shown in Fig. 2. Supplemental Movie 1 [34] shows an example of PMMA tracer-particle motions around a silicone oil drop at three planes, corresponding to three heights h_p , with particles at each height distinguished via false color as red, green, and blue.

III. BACKGROUND AND THEORY

The mean-squared displacement or the second moment of a Gaussian distribution, in one dimension, is defined by

$$\langle [x(t)]^2 \rangle = \int_{-\infty}^{\infty} x^2 P_G(x,t) \, dx = 2Dt, \tag{1}$$

where

$$P_G(x,t) = \frac{1}{\sqrt{4\pi Dt}} \exp\left(\frac{-x^2}{4Dt}\right).$$
 (2)

 $P_G(x, t)$, *D*, and *t* represent the Gaussian probability distribution of displacements *x*, diffusion coefficient with dimension $[D] = m^2 s^{-1}$, and time, respectively [18,35]. The Gaussian-diffusive trajectories are characterized by irregular, but small and homogeneous, steps.

Diffusion processes in many complex systems do not follow Gaussian statistics, and the mean-squared displacement (MSD) does not vary linearly in time: this is expressed (in d dimensions) by

$$MSD = 2dK_{\gamma}t^{\gamma}, \qquad (3)$$

where K_{γ} is a generalized diffusion constant with dimension $[K_{\gamma}] = m^2 s^{-\gamma}$ and γ is the anomalous diffusion exponent, with subdiffusive motions corresponding to $0 < \gamma < 1$ and superdiffusive motions corresponding to $1 < \gamma < 2$.

The MSD is simply the second moment of the underlying probability distribution of displacements. Various anomalous diffusion processes yield fractional ($\gamma \neq 1$) dynamics [36,37]. The simplest generalization to the Gaussian probability distribution function of Brownian motion is given by the models of fractional Brownian motion as well as the generalized Langevin equation, which both yield

$$P(x,t) = \frac{1}{\sqrt{4\pi K_{\gamma} t^{\gamma}}} \exp\left(\frac{-x^2}{4K_{\gamma} t^{\gamma}}\right), \tag{4}$$

where $0 < \gamma \leq 2$.

Enhanced diffusion with a 3/2 power law has been related to the random velocity field model, first described by Matheron *et al.* [38] to understand water transport in microscopically heterogeneous rocks. This model describes coupling between diffusion and random but spatially correlated velocities: a particle diffuses in a stratified fluid where each layer of fluid has a random velocity. Redner [10], Zumofen *et al.* [9], and Bouchaud *et al.* [8] obtained the probability distribution of displacements for diffusion in random velocity fields:

$$P(x,t) = \frac{A}{\sqrt{t^{3/2}}} \exp\left[-\left(\frac{x^2}{4K_{\gamma}t^{3/2}}\right)^{\delta/2}\right].$$
 (5)

In the above, A is the normalization factor with dimension $[A] = m^{-1}s^{3/4}$, and K_{γ} is the generalized diffusion constant. δ is a parameter that is not fully determined within the model but is expected to be less than 1.7, while the asymptotic behavior considering large displacements suggests $\delta \leq 4/3$ [10].

The deviation of the distribution function from a Gaussian also can be quantified using both the second moment, $\langle x^2 \rangle$, and the fourth moment, $\langle x^4 \rangle$, of the distribution of displacements (in one dimension) using the non-Gaussian parameter [39]:

$$\alpha_2 = \frac{\langle x^4 \rangle}{3 \langle x^2 \rangle^2} - 1. \tag{6}$$

The value of α_2 is a sensitive measure for the type of anomalous diffusion. For Gaussian-distributed displacements $\alpha_2 = 0$, while this parameter deviates from zero for non-Gaussian distributions.

In the tracer-particle tracking experiments in this work, we can readily obtain mean-squared displacements as well the fourth moments as a function of time; we can therefore obtain the value of γ as well as α_2 . For short times, we can also construct the entire probability distribution of displacements P(x, t) with reasonable precision, but out-of-plane escape of particles at long times limits doing so for all times.

IV. RESULTS AND DISCUSSION

A. Non-Gaussian distributions

The probability distribution of particle displacements in the x and y directions, as a function of t, is calculated based on the trajectories by averaging over all start times t_0 and particles. An example of P(x, t) is shown in Fig. 3 for $E = 3.5 \text{ V}/\mu\text{m}$, at $h_p = 10 \ \mu m$, for 0.5, 1, 2, and 6 Hz and for different times. P(x, t) is obtained only for short times, as the statistics gets progressively poorer for longer times. The distribution at short times is distinctly non-Gaussian. Equation (5) is used to fit the probability distributions. For the short times examined, there is good agreement. Decreasing the field amplitude corresponds to lowering the driving, and so does increasing field frequency, because it takes us from the strong to the weak hydrodynamic regime (as described in earlier work [25,30]). With increasing frequency, we find that the fits are not as good at large displacements. In a few data sets, the P(x, t) are asymmetric: these data were not fit. These asymmetries likely arise from drop size nonuniformities, which result in local drifts inside the cell.

From the above fits, one can get the unknown parameter δ , shown in Fig. 3(e). The value $\delta = 1.04 \pm 0.12$ is experimentally consistent with $\delta = 1$, which is a simple exponential

dependence on the absolute value of the displacement. We note, first, that these distributions have been obtained only for short times, which correspond to small overall displacements, and the behavior at long times could be very different. While $\gamma = 3/2$ and $\delta \simeq 1$ is consistent with the prediction of $\gamma = 3/2$ and $\delta \leqslant 1.7$ in the random velocity field model, we emphasize that the flows here are different. In the random velocities in different strata by diffusing between strata, while in the current system, all the unsteady motions are driven motions. Supplemental Movie 2 [34] shows that the velocities in the plane are isotropic and spatially varying because they enter into the plane and emanate outward from each of the trapped drops (see Fig. 2) and exit out of the plane between the drops.

B. Dynamics: Anomalous superdiffusive transport

Next, we examine the dynamics of particles, as a function of frequency, field amplitude, and height, via the mean-squared displacement (MSD) of tracer-particles centroids. Since the motions are isotropic in the plane (i.e., $\langle x^2 \rangle = \langle y^2 \rangle$), the 2D mean-squared displacement, $MSD = \langle x^2 \rangle + \langle y^2 \rangle$, is plotted instead. Figure 4(a) shows an example of log(MSD) versus $\log(t)$ for $E = 3.5 \text{ V}/\mu\text{m}$ for different frequencies and three heights of interest over a 10 s time interval. A longer time analysis of roughly about 40 s, equivalent to a stack of 400 frame recorded at 10 fps, is also carried out. Two examples presented in Fig. 4(b) show the mean-squared displacement, MSD, of PMMA particles over a 100-frame and a 400-frame image stack. Increasing the number of frames, consequently the time of analysis, does not change the slope of the MSD-time plot. It also does not affect the limiting maximum time at which the MSD sharply decreases. This is likely because the limiting time is not the duration of observation but the time the particles remain in the plane. For all fields, heights, and frequencies, the dependence, viewed on a log-log scale, is linear and the slope is close to 3/2. The value of γ for each field amplitude as a function of height is reported in Fig. 4(b), while the average value of $\gamma = 1.52 \pm 0.01$.

There could be multiple origins for the 3/2 power law. Fractional tracer dynamics with a power law exponent $\gamma \approx 3/2$ has been reported theoretically and experimentally. A numerical study of Lévy random walks [11] finds superdiffusive transport with $\gamma \simeq 1.47$; the probability distribution function is a modified Gaussian for short displacements but a power law for large displacements. In experiments, Caspi et al. [12,13] reported superdiffusive motions with a $t^{3/2}$ scaling at short times for the MSD of a microsphere inside a living cell. They argued that a time-dependent friction imposed by the non-Newtonian medium of the living cell is responsible for the power law scaling behavior. Regner et al. [40] showed theoretically and experimentally that interacellular transport, cytoskeletal transport along microtubules, follows fractional Brownian motion with power law scaling of 3/2 for short and long lag times.

One also can measure the non-Gaussian parameter, α_2 , from the second and the fourth moment of the probability distribution of displacements. As a practical matter, the second and fourth moments probe large displacements more efficiently, and so this can be compared with the probability



FIG. 3. Normalized histogram: panels (a)–(d) show four examples of the normalized distribution histograms along x and y in three successive times and at four different frequencies, 0.5, 1, 2, and 6 Hz, respectively. $E = 3.5 \text{ V}/\mu\text{m}$, perpendicular to the page and $h_p = 10 \mu\text{m}$. (e) Variation of δ versus f gives rise to mean value of 1.04 ± 0.12 .

distributions obtained at short times and, hence, small displacements. Plotted in Figs. 5(a) and 5(b) for one field amplitude, $E = 3.5 \text{ V}/\mu\text{m}$ and frequency f = 0.5 Hz, one sees that $\langle x^2 \rangle$ and $\langle y^2 \rangle$ have a linear relationship to $t^{1.5}$ [Fig. 5(a)], while $\langle x^4 \rangle$ and $\langle y^4 \rangle$ have a linear relation to t^3 [Fig. 5(b)]. Fitting to the linear forms, $\langle x^2 \rangle = K_{\gamma}t^{1.5}$, $\langle y^2 \rangle = K_{\gamma}t^{1.5}$ and $\langle x^4 \rangle = K_{2\gamma}t^3$ and $\langle y^4 \rangle = K_{2\gamma}t^3$, one can explicitly obtain for the probability distribution in Eq. (5):

$$\alpha_2 = \frac{K_{2\gamma}}{3K_{\gamma}^2} - 1. \tag{7}$$

For all field amplitudes, α_2 is plotted in Fig. 5(c) as a function of the field frequency. While the results show more dispersion than those for γ , averaging over *all* data sets yields a value of $\alpha_2 = 0.31 \pm 0.06$. Within errors there is possibly an inverse relationship of α_2 with frequency (light gray line in Fig. 5(c)). For the probability distribution in Eq. (5), α_2 can be calculated given a value of δ : $\alpha_2 = 0.31 \pm 0.06$ corresponds to $\delta = 1.43 \pm 0.06$. This is larger than $\delta = 1$, obtained for short times, and interestingly, close to the asymptotic value $\delta \simeq 4/3$ for large displacements in the random-velocity-field model [10].



FIG. 4. (a) log(MSD) versus log(t) shows a linear dependency with the slope of $\gamma \simeq 1.5$ consistent with enhanced superdiffusive dynamics in the outer fluid. $\gamma \simeq 1.5$ is independent of frequency, field amplitude, and the height above the bottom electrode (i.e., the x-y plane) at which the experiment is carried out. (b) MSD versus time for short time, 100 frames recorded at 20 fps for 0.5 Hz and 10 fps for 4 Hz equivalent to 5 and 10 s, respectively. MSD versus time for long time, 400 frames recorded at 20 fps for 0.5 Hz and 10 fps for 4 Hz equivalent to 20 and 40 s, respectively. (c) γ versus h_p , which is averaged over frequency and amplitude, respectively, shows a mean value of $\gamma = 1.52 \pm 0.01$.

C. Hydrodynamic length scales

Next, the generalized diffusion constant, K_{γ} , is shown in Fig. 6(a). This was obtained directly from the MSD-time plot in Fig. 4(a). By rewriting Eq. (3) as $\log(MSD) = \log(4K_{\gamma}) + \gamma \log(t)$, K_{γ} was simply obtained from the *y*-intercept of a linear fit to each data set in Fig. 4(a). K_{γ} decreases with increasing frequency. This is consistent with decreasing particle diffusivity in the outer fluid. From K_{γ} , we can construct a length scale $\lambda_h = \sqrt{K_{1.5}/f^{1.5}}$. λ_h is an average length one



FIG. 5. (a) The second moment of the distribution of displacements along x and y depends linearly on $t^{1.5}$: the slope $K_{\gamma} = 12.3 \pm 0.1 \,\mu\text{m}^2/\text{s}^{1.5}$ (b) The fourth moment of x and y distribution of displacements depends linearly on t^3 : the slope $K_{2\gamma} = 648.6 \pm$ 7.1. (c) The non-Gaussian parameter has an approximate inverse frequency dependence (shown by the light gray line), with an average value $\alpha_2 = 0.31 \pm 0.06$. The inset shows α_2 calculated from Eq. (5) for different values of the, in principle, unknown δ parameter. A value $\alpha_2 = 0.31 \pm 0.06$ corresponds to $\delta = 1.43 \pm 0.06$.

particle moves in one period of the ac oscillation, i.e., f^{-1} s. λ_h versus frequency is plotted in Fig. 6(b) and shows a decreasing trend by increasing frequency.

The ion mobility length, l_h , is a characteristic length representing the range of the electrohydrodynamic interactions. l_h can be increased by decreasing the frequency, f, because $l_h = v_d/f$, where $v_d = \mu_E E$ is the ionic drift velocity. v_d , in turn, is defined by electric mobility, μ_E , and the electric field amplitude, E. The electric mobility is described by $\mu_E = z_i e_0/6\pi r \mu_{ex}$ where $z_i e_0$ is the ions charge, and r is the radius of the ions [41]. As a result, l_h is a quantity set by $l_h \propto E/f$. For castor oil, as the carrier fluid, with $\mu_{ex} =$



FIG. 6. (a) Effective diffusion coefficient, K_{γ} , versus f. (b) An experimental length scale, $\lambda_h = \sqrt{K_{1.5}/f^{1.5}}$, versus frequency, f, for different field amplitudes, frequencies, and heights, shows a monotonic decrease with increasing f. (c) An expected ionic hydrodynamic length, $l_h = \mu_E E/f$, plotted for all field amplitudes for comparison with λ_h . (d) Experimental length scale, λ_h , versus ionic hydrodynamic length scale, l_h , shows a linear dependency with an x intercept of $l_0 \simeq 40 \ \mu m$.

0.819 Pa s, $z_i e_0 = 1.6 \times 10^{-19}$ C, and $r \simeq 140 \times 10^{-12}$ m, the electric mobility is $\mu_E \simeq 75 \ \mu \text{m}^2 \text{V}^{-1} \text{s}^{-1}$. Figure 6(c) shows l_h versus frequency for all field amplitudes and frequencies used in this work. l_h at low frequencies is about one order of magnitude larger than λ_h ; however, they show a remarkably similar frequency dependence.

In Fig. 6(d) we plot λ_h versus l_h for all field amplitudes and frequencies. λ_h versus l_h shows a remarkably linear dependence, but with an *x*-intercept of roughly $l_0 \simeq 40 \ \mu$ m. This indicates that λ_h can be considered to be a kind of *lateral* hydrodynamic length. In contrast to l_h , it is determined experimentally. λ_h is nonzero only above a combination of field and frequency set by $l_h \propto E/f$. The *x* intercept, l_0 , is an interesting quantity that possibly indicates that there is a minimum threshold of (solvent) ionic displacement required in order to initiate fluid flow. At zero field, the system is heavily overdamped, and there are no observable motions at all.

V. CONCLUSION

We have carefully characterized tracer motions, via particle tracking, in an electrohydrodynamically driven system where a spatially varying and time-dependent driving can be realized. Experiments have been carried out as a function of the amplitude and frequency of the external electric field.

We find a robust $t^{3/2}$ power-law for superdiffusive motions in this system, and we are able to extract the mathematical form of the underlying probability distribution of displacements, at least for short times. In particular, the parameter δ can be obtained both for short times, and small displacements, and for long times, and larger displacements. Its value is consistent with $\delta \simeq 1$ at short times, which corresponds to a probability distribution function with a simple exponential dependence on displacement, For longer times, we find $\delta \simeq 1.4$, close to the asymptotic value $\delta \leq 4/3$ obtained for large displacements in the random-velocity-field model [10]. In this model, random velocities in different strata are coupled in by particle diffusion between strata, while in the current system, all the unsteady motions are driven motions. It is interesting that a variety of experimental systems, with different underlying driving forces, display the 3/2-power superdiffusive behavior. This suggests a generic origin that is insensitive to the model details.

Finally, from the tracer motions, we find that we can extract a (frequency- and amplitude-dependent) hydrodynamic length scale. This length scale reports on the length over which tracerparticle motions are correlated and in that sense is like the lateral (in-plane) range of hydrodynamic interactions in the system. We also measured the minimum ion mobility length, l_0 , required to initiate persistent flows. We hope that this particle tracking study in a simplified geometry, where the droplet positions are fixed, will encourage theoretical attention via simulations of this electrohydrodynamics problem.

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